

Efficient parallel CP decomposition with pairwise perturbation and multi-sweep dimension tree

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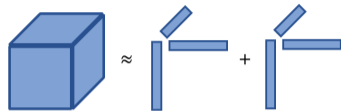
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Background

CP tensor decompositions

$$\mathbf{X} \approx \sum_{r=1}^R \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r,$$



- Consider $\mathbf{X} \in \mathbb{R}^{s \times s \times s}$, and the CP rank $R \ll s$

Alternating least squares (**CP-ALS**) updates factors in an alternating manner

$$\min_{\mathbf{a}_1, \dots, \mathbf{a}_R} \frac{1}{2} \left\| \sum_{r=1}^R \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r - \mathbf{X} \right\|_F^2 \rightarrow \min_{\mathbf{A}} \frac{1}{2} \left\| (\mathbf{C} \odot \mathbf{B}) \mathbf{A}^T - \mathbf{X}_{(1)}^T \right\|_F^2$$

$$\min_{\mathbf{b}_1, \dots, \mathbf{b}_R} \frac{1}{2} \left\| \sum_{r=1}^R \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r - \mathbf{X} \right\|_F^2 \rightarrow \min_{\mathbf{B}} \frac{1}{2} \left\| (\mathbf{C} \odot \mathbf{A}) \mathbf{B}^T - \mathbf{X}_{(2)}^T \right\|_F^2$$

$$\min_{\mathbf{c}_1, \dots, \mathbf{c}_R} \frac{1}{2} \left\| \sum_{r=1}^R \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r - \mathbf{X} \right\|_F^2 \rightarrow \min_{\mathbf{C}} \frac{1}{2} \left\| (\mathbf{B} \odot \mathbf{A}) \mathbf{C}^T - \mathbf{X}_{(3)}^T \right\|_F^2$$

Background of CP-ALS

$$\min_{\mathbf{A}} \frac{1}{2} \left\| (\mathbf{C} \odot \mathbf{B}) \mathbf{A}^T - \mathbf{X}_{(1)}^T \right\|_F^2 \implies \mathbf{A} \leftarrow \mathbf{X}_{(1)} (\mathbf{C} \odot \mathbf{B}) \left((\mathbf{C}^T \mathbf{C}) * (\mathbf{B}^T \mathbf{B}) \right)^{-1}$$

- $\mathbf{A} = [\mathbf{a}_1, \dots, \mathbf{a}_R] \in \mathbb{R}^{s \times R}$, similar for \mathbf{B} , \mathbf{C}
- $\mathbf{X}_{(1)} \in \mathbb{R}^{s \times s^2}$ is the first mode matricization of \mathbf{X}
- Matricization in the first mode maps tensor element (i_1, i_2, i_3) to matrix element $(i_1, (i_2 - 1)s + i_3)$
- $\mathbf{C} \odot \mathbf{B} \in \mathbb{R}^{s^2 \times R}$ is the Khatri-Rao Product (KRP) of \mathbf{C} , \mathbf{B}
- $\mathbf{C} \odot \mathbf{B} := [\mathbf{c}_1 \otimes \mathbf{b}_1, \dots, \mathbf{c}_R \otimes \mathbf{b}_R]$
- $\mathbf{X}_{(1)} (\mathbf{C} \odot \mathbf{B})$: MTTKRP, main bottleneck, costs $4s^N R$ flops

Our contributions

- We introduce a new **multi-sweep dimension tree (MSDT)** algorithm to reduce the leading computational cost
- We introduce a communication-efficient distributed parallel **pairwise perturbation (PP)** algorithm (focus of the talk)
- At least **1.52X** speed-ups compared to the state-of-the-art CP-ALS

	Computational cost	Horizontal communication cost
ALS	$4s^N R \cdot \gamma$	$\mathcal{O}(N \log(P) \cdot \alpha + NsR/P^{\frac{1}{N}} \cdot \beta)$
MSDT	$\frac{2N}{N-1} s^N R \cdot \gamma$	$\mathcal{O}(N \log(P) \cdot \alpha + NsR/P^{\frac{1}{N}} \cdot \beta)$
PP-init	$4s^N R \cdot \gamma$	/
PP-approx	$2N^2(s^2 R + R^2) \cdot \gamma$	$\mathcal{O}(N \log(P) \cdot \alpha + NsR/P^{\frac{1}{N}} \cdot \beta)$

Cost based on the BSP $\alpha - \beta - \gamma$ model

Pairwise perturbation algorithm (L. Ma et al, arxiv 1811.10573)

- Main idea of the PP algorithm: approximate the MTTKRP $\mathbf{M}^{(1)} = \mathbf{X}_{(1)}(\mathbf{B} \odot \mathbf{C})$
- Let \mathbf{B}_p denote the \mathbf{B} calculated at some iteration prior to the current one
- $\mathbf{B} = \mathbf{B}_p + d\mathbf{B}$, $\mathbf{C} = \mathbf{C}_p + d\mathbf{C}$

$$\begin{aligned}\mathbf{M}^{(1)} &= \mathbf{X}_{(1)}\left((\mathbf{B}_p + d\mathbf{B}) \odot (\mathbf{C}_p + d\mathbf{C})\right) \\ &= \mathbf{X}_{(1)}(\mathbf{B}_p \odot \mathbf{C}_p) + \mathbf{X}_{(1)}(\mathbf{B}_p \odot d\mathbf{C}) + \mathbf{X}_{(1)}(d\mathbf{B} \odot \mathbf{C}_p) + \mathbf{X}_{(1)}(d\mathbf{B} \odot d\mathbf{C}) \\ &\approx \mathbf{X}_{(1)}(\mathbf{B}_p \odot \mathbf{C}_p) + \mathbf{X}_{(1)}(\mathbf{B}_p \odot d\mathbf{C}) + \mathbf{X}_{(1)}(d\mathbf{B} \odot \mathbf{C}_p) := \widetilde{\mathbf{M}}^{(1)}\end{aligned}$$

Pairwise perturbation contains two steps:

- Initialization step: calculates $\mathbf{X}_{(1)}(\mathbf{B}_p \odot \mathbf{C}_p)$, $\mathbf{X}_{(1,3)}\mathbf{B}_p$, $\mathbf{X}_{(1,2)}\mathbf{C}_p$ (overall cost $O(s^N R)$)
- Approximated step: finish the calculation of $\mathbf{X}_{(1)}(\mathbf{B}_p \odot d\mathbf{C})$, $\mathbf{X}_{(1)}(d\mathbf{B} \odot \mathbf{C}_p)$ (overall cost $O(Ns^2 R)$)

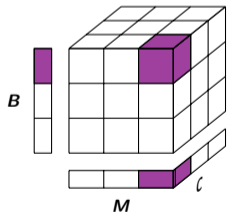
Parallel MTTKRP (G. Ballard et al, HiPC 2018)

Main idea: decompose MTTKRP into local MTTKRP to reduce the communication cost

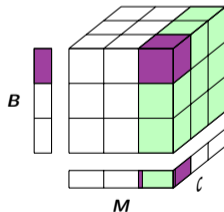
- Input tensor uniformly distributed across the processor grid \mathcal{P}
- $\mathbf{X}_{\mathcal{P}(i,j,k)}$ denotes the local data on the processor $\mathcal{P}(i,j,k)$
- Perform local MTTKRP on each processor

$$\mathbf{M}_{\mathcal{P}(i,j,k)} = \text{Local-MTTKRP}(\mathbf{X}_{\mathcal{P}(i,j,k)}, \mathbf{B}_{\mathcal{P}(i,j,k)}, \mathbf{C}_{\mathcal{P}(i,j,k)}),$$

- Perform reduce-scatter on $\mathbf{M}_{\mathcal{P}(i,j,k)}$ to uniformly distribute \mathbf{M}



(a) Compute local MTTKRP



(b) Perform reduce-scatter

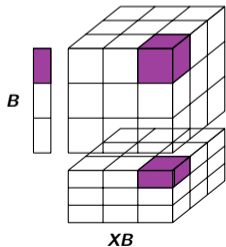
Parallel pairwise perturbation

PP initialization step

- Perform local partial MTTKRP contraction

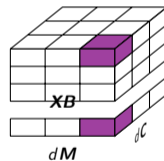
$$\mathbf{X}\mathbf{B}_{\mathcal{P}(i,j,k)} = \mathbf{X}_{(1,3)\mathcal{P}(i,j,k)} \mathbf{B}_{p\mathcal{P}(i,j,k)}$$

- No communication needed
- More memory needed

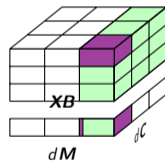


PP approximated step

- Computing local MTTKRP updates
- Communication cost same as parallel MTTKRP

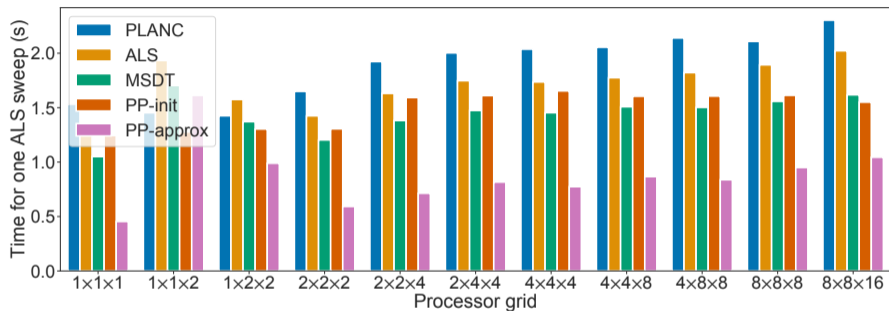


(a) Local MTTKRP update



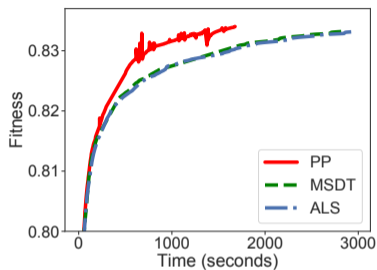
(b) Perform reduce-scatter

Weak scaling benchmark results

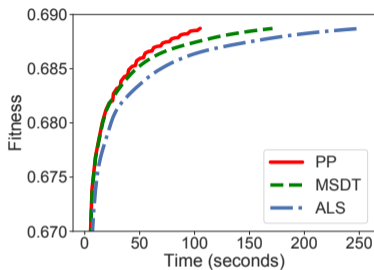


- Rank $R = 400$, and the local tensor size $400 \times 400 \times 400$
- PP approximated step has up to 2X speed-up compared to state-of-art ALS (S. Eswar et al, [arxiv 1909.01149](https://arxiv.org/abs/1909.01149))

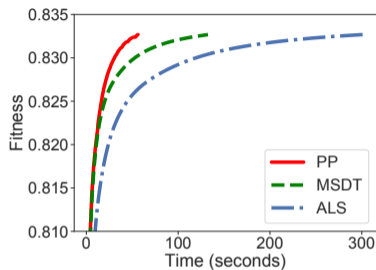
Performance on real data



(a) Quantum chemistry tensor



(b) Coil dataset



(c) Timelapse dataset

- Tensor size: (a) $4520 \times 280 \times 280$ (b) $128 \times 128 \times 3 \times 7200$ (c) $1024 \times 1344 \times 33 \times 9$
- CP rank: (a) $R = 1000$ (b) $R = 20$ (c) $R = 50$
- Up to 5.4X speed-up

Contributions

- We introduce a communication-efficient distributed parallel **pairwise perturbation (PP)** algorithm
- We introduce a new **multi-sweep dimension tree (MSDT)** algorithm to reduce the leading computational cost
- At least **1.52X** speed-ups compared to the state-of-the-art CP-ALS

Other details

- PP and MSDT are vertical communication/memory bandwidth bound